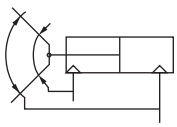
Air gripper(180° open/close type)

HFR Series

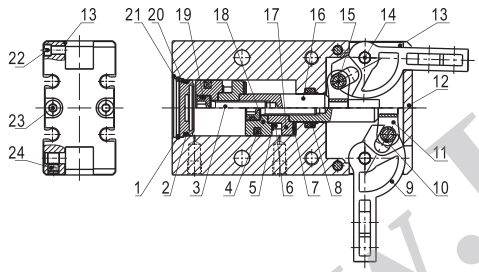
Symbol



Product feature

1. open/close type, simplify the gripping action.
2. A sheet metal is installed between the finger and body to reduce abrasion and extend the service life.
3. Dust proof is designed in the finger part, which is applicable to special working environment.
4. All series are all attached with magnet.
5. Many mounting types to be choosed.

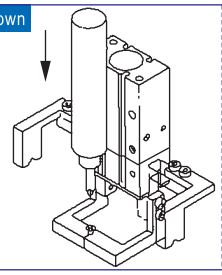
Inner structure and material of major parts



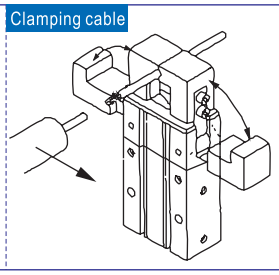
NO.	Item	Material	NO.	Item	Material
1	C clip	Spring steel	12	Front cover	Aluminum alloy
2	O–ring	NBR	13	Sheet metal	Stainless steel
3	Countersink screw	Carbon steel	14	Pin	Stainless steel
			15	Pin	Stainless steel
4	Piston seal	NBR	16	Piston rod	Stainless steel
5	Magnet washer	NBR	17	Magnet holder	Aluminum alloy
6	Magnet	Sintered metal (Neodymium-iron-ioron)	18	Piston	Aluminum alloy
			19	O–ring	NBR
7	Bumper	TPU	20	Back cover	Aluminum alloy
8	Rod packing	NBR	21	Body	Aluminum alloy
9	Gripping jaws	Stainless steel	22	Pin	Stainless steel
10	Pin sheath	Stainless steel	23	Countersink screw	Carbon steel
11	Push block	Stainless steel	24	Countersink screw	Carbon steel

Example

Screw down



Clamping cable



Specification

Bore size (mm)	10	16	20	25	32
Acting type	Double acting				
Fluid	Air(to be filtered by 40 μ m filter element)				
Operating pressure	0.15~0.7MPa(21~100psi)(1.5~7.0bar)				
Temperature ℃	-10~70				
Lubrication	Cylinder：Not required； Gripper jaws：Lubricate grease				
Cushion type	Bumper				
Max. frequency	60(c.p.m)				
Repeatability	± 0.2mm				
Gripping force ①	0.16N.m	0.55N.m	1.10N.m	2.30N.m	5.00N.m
Open or close angle	Open: -2° ~ -5° Close: 180° ± 2°				
Port size	M5 × 0.8				
Sensor switches ②	DS1-H				

① The gripping force is the value when the operating pressure is 0.5Mpa.
② Sensor switch should be ordered additionally, please refer to P397~420 for detail of sensor switch.

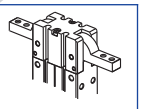
Ordering code

HFR 20 □

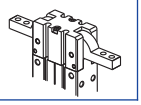
Model
HFR: 180° open/close air gripper

Bore size
10: Φ10mm
16: Φ16mm
20: Φ20mm
25: Φ25mm
32: Φ32mm

Mounting type
Blank: Mounting through tapped holes

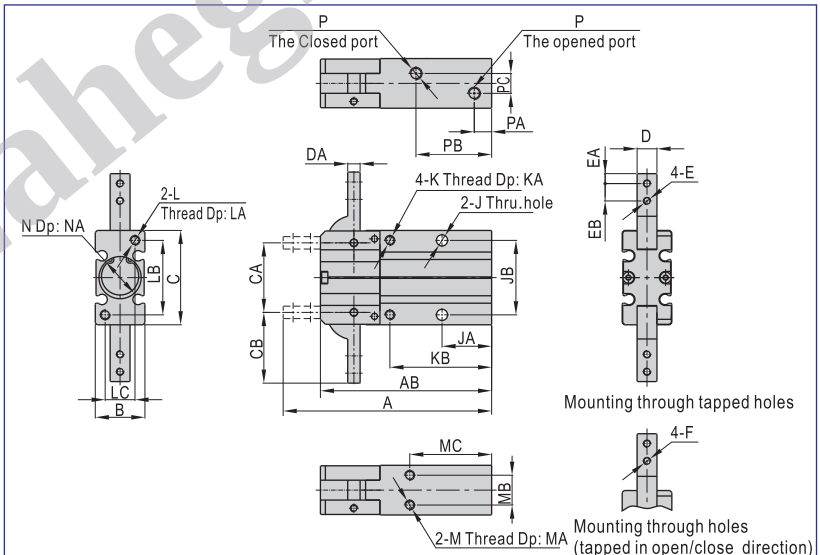


N: Mounting through holes (tapped in open/close direction)



① HFR series are all attached with magnet.

Dimensions



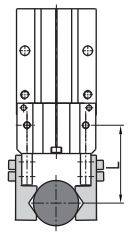
Model\Item	A	AB	B	C	CA	CB	D	DA	E	F	EA	EB
10	71	58	15	30	22	23.5	6	4	M3 × 0.5	Φ3.3	3	6
16	84	69	20	38	28	28.5	8	5	M3 × 0.5	Φ3.3	4	7
20	106	86	26	48	36	37	10	8	M4 × 0.7	Φ4.5	5	9
25	131	107	30	58	45	45	12	10	M5 × 0.8	Φ5.5	6	12
32	158.5	122	40	72	55	62.5	14	12	M6 × 1.0	Φ6.5	9	16

Model\Item	J	JA	JB	K	KA	KB	L	LA	LB	LC
10	Φ3.3	18	24	M3 × 0.5	6	35	M3 × 0.5	6	24	9
16	Φ4.5	20	30	M4 × 0.7	8	41	M4 × 0.7	8	30	12
20	Φ5.5	25	36	M5 × 0.8	10	50	M5 × 0.8	10	38	16
25	Φ6.5	30	42	M6 × 1.0	12	60	M6 × 1.0	12	46	18
32	Φ6.5	35	46	M6 × 1.0	12	64	M6 × 1.0	14	46	26

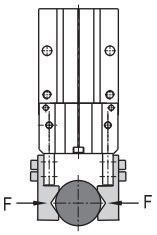
Model\Item	M	MA	MB	MC	N	NA	P	PA	PB	PC
10	M3 × 0.5	4	9	30	$\Phi 11\ ^{+0.05}_{0}$	1.5	M5 × 0.8	7	28.5	3
16	M4 × 0.7	5	12	33	$\Phi 17\ ^{+0.05}_{0}$	1.5	M5 × 0.8	7	30.5	8
20	M5 × 0.8	8	14	42	$\Phi 21\ ^{+0.05}_{0}$	1.5	M5 × 0.8	8	38.5	12
25	M6 × 1.0	10	16	50	$\Phi 26\ ^{+0.05}_{0}$	1.5	M5 × 0.8	8	48	14
32	M6 × 1.0	12	26	59	$\Phi 34\ ^{+0.05}_{0}$	2	M5 × 0.8	9	56	18

How to select product

1. Confirmation of effective gripping force
   1.1) Though the coefficient of friction between the attachments and the workpiece is different, select a gripping force which is 10 to 20 times greater than the workpiece weight.
   1.2) If high acceleration or impact forces are encountered during motion, a further margin of safety should be considered.
   Example: When the workpiece weight is 0.05 and the gripping point distance L is 30mm, the operating pressure will be 5kgf/cm^2.
   Effective gripping force=0.05kg×20 times×9.8m/s^2=more than 10N
   Model selection: HFR16 is recommended. The effective gripping force is 17N, which is 20 times greater than the set value of gripping force.
   1.3) The finger thrust is expressed as F, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

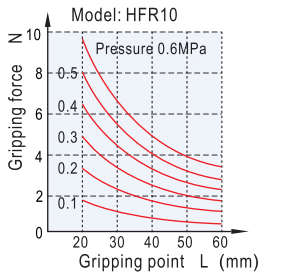


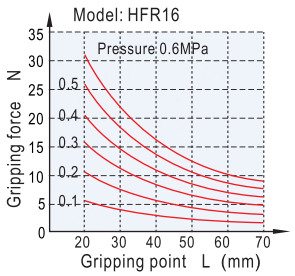
L: Gripping point

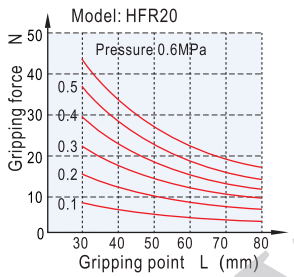


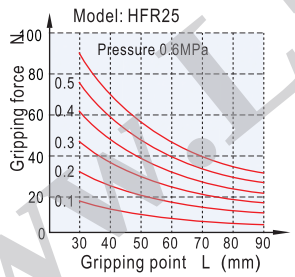
F: Single finger thrust

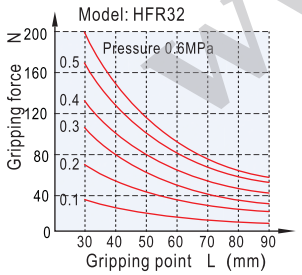
2. Connection between gripping force and gripping point distance



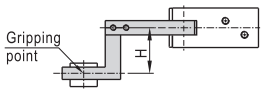


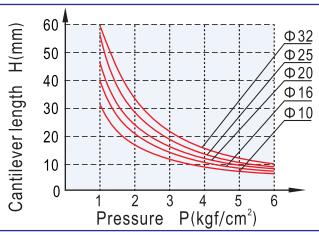






3. The selection of the gripping point
   3.1) Please select the gripping point within the limited field shown left.Over the limits, gripping jaws would be subjected to excessive torque loads, and lead to short life of the air gripper.
   3.2) In the allowable range of gripping point, it is better to design for short and light fittings. If the fittings are long and heavy, the inertia force when the finger is open and close will become larger, and the performance of gripping jaw will be degraded, at the same time it will affect the life.

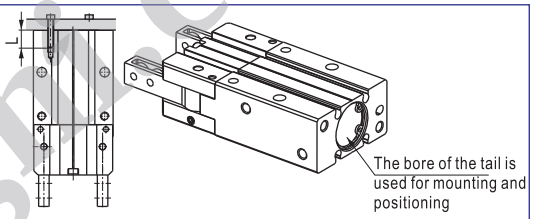




Installation and application

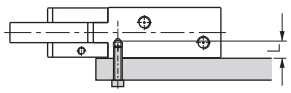
1. Due to the abrupt changes, the circuit pressure is low, which will lead to the decrease of the gripping force and falling of the work-pieces. In order to avoid the harm to the human body and damage to the equipment, anti-dropping device must be equipped.
2. Don't use the air gripper under strong external force and impact force.
3. When install and fix the air gripper, avoid falling down, collision and damage.
4. When fixing the gripping jaw parts, don't twist the gripping jaw.
5. There are several kinds of installation method, and the locking torgue of fastening screw must be within the prescribed torque range shown in the below chart. If the locking torque is too large, it will cause the dysfunctional. If the locking torque is too small, it will cause the position deviation and fall.

Tail installation type



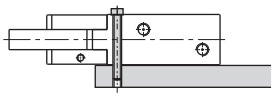
Bore size	The bolts type	Max. locking moment (Nm)	Max. screwed depth (mm)	The aperture of the positioning bore(mm)	The depth of the positioning bore(mm)
10	M3 × 0.5	1	6	Φ11H9	1.5
16	M4 × 0.7	2	8	Φ17H9	1.5
20	M5 × 0.8	4.5	10	Φ21H9	1.5
25	M6 × 1.0	7	12	Φ26H9	1.5
32	M6 × 1.0	7	14	Φ34H9	2

The installation of the front threaded hole



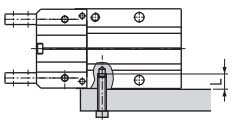
Bore size	The bolts type	Max. locking moment (Nm)	Max. screwed depth (mm)
10	M3 × 0.5	1	6
16	M4 × 0.7	2	8
20	M5 × 0.8	4.5	10
25	M6 × 1.0	7	12
32	M6 × 1.0	7	14

The installation of the front through hole



Bore size	The bolts type	Max. locking moment (Nm)
10	M3 × 0.5	1
16	M4 × 0.7	2
20	M5 × 0.8	4.5
25	M6 × 1.0	7
32	M6 × 1.0	7

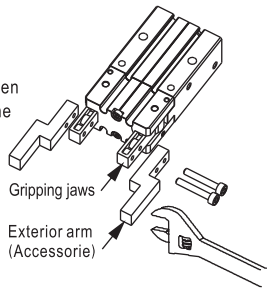
Surface installation type



Bore size	The bolts type	Max. locking moment (Nm)	Max. screwed depth (mm)
10	M3 × 0.5	0.6	4
16	M4 × 0.7	1.5	5
20	M5 × 0.8	3.5	8
25	M6 × 1.0	6	10
32	M6 × 1.0	6	12

6. The installation method of the gripping jaw fittings
When install the gripping jaw fittings, you have to pay particular attention that you can only hold the gripping jaw by using spanner, and then lock the screws with allen wrench. Never clamp the body directly and then lock the screws, otherwise the parts will be easily damaged.

Boresize	The bolts type	Max. locking moment (Nm)
10	M3 × 0.5	0.6
16	M3 × 0.5	0.6
20	M4 × 0.7	0.8
25	M5 × 0.8	1.5
32	M6 × 1.0	3



7. Other contents of installation and operation are the same with those of HFY. Refer to the "Installation and Operation" instruction of HFY.